# 4/4 B.Tech. SEVENTH SEMESTER

ME7L2	MACHINE DYNAMICS LAB	Credits: 2

Lecture:-	Internal assessment: 25marks
Practice: 3 periods/week	Semester end examination: 50 marks

## **Objectives:**

- 1. Determine the vibration parameters of a vibrating system
- 2. Predict the radius of gyration and moment of inertia of vibrating system
- 3. Check the static and dynamic balancing
- 4. Study the effect of gyroscopic couple and operations of robotic arm

#### Learning outcomes:

At the end of course the students will be able to:

- 1. Evaluate the natural frequencies in different vibrating systems
- 2. Compute the radius of gyration & Moment of Inertia of oscillating part in vibration system
- 3. Apply the concepts of damping to reduce vibration in dynamic system
- 4. Mention the amplitude of vibration in damped and undamped vibrating system
- 5. Test the static balancing, dynamic balancing and effect of gyroscopic couple
- 6. Implement the operations to manipulate the robot arm in industries

## **Prerequisites:**

Dynamics of Machinery

Any 12 Experiments from following

## LIST OF EXPERIMENTS

- 1. Natural frequency of single mass, single helical spring system.
- Natural frequency of combination of springs springs in parallel or springs in series
- 3. Natural frequency of undamped torsional single rotor system

- 4. Determination of radius of gyration of a given compound pendulum
- 5. Determination of radius of gyration, moment of inertia bifilar suspension method
- 6. Damping coefficient of torsional single rotor system Effect of depth of immersion in oil and damping ratio
- 7. Determination of amplitude of vibration of damped vibrating system.
- 8. Determination of amplitude of vibration of undamped vibrating system.
- 9. Static balancing using steel balls
- 10. Dynamic balancing using steel balls.
- 11. Whirling of shafts/ determination of critical speed with and with out Rotors.
- 12. Gyroscopic couple verification.
- 13. Palletizing operation using Robot Arm
- 14. Direct Kinematic Analysis of Robot Arm